

Industrial Process Control MDP 454

- Course aims:
 - Understand the classic control strategies
 - Understand the artificial intelligent systems
 - Create and innovate the real model to simulate the some cases
- References
- •Dorf, R. C., & Bishop, R. H. (2001). Modern control systems. Upper Saddle River, NJ: Prentice Hall. (Ref-01)
- •Burns, R. S. (2001). Advanced control engineering. Oxford: Butterworth-Heinemann. (Ref-02)

Course plan

w	eek	Date	Contents	Requirements	Laboratory	References	Marks
	1	24-9	Introduction Syllable/Course specs Control system classifications System Modeling				
	2	1-10	Mathematical Modeling (Mechanical-Hydraulic)		Sensor and instrumentation		
	3	8-10	Modeling (electrical system and motors)			Ref-01	5/3 quizes
	4	15-10	Modeling of combined systems Block diagram		Electrical- mechanical analogy		
	5	22-10	Transfer function and State space				5/3 quizes
	6	29-10	Time Response (2 nd order)		Filters		•
	7	5-11	steady state Error, Stability analysis				
	8	12-11	Midterm				15

Course plan

week	Date	Contents	Requirements	Laboratory	References	Marks
9	19-11	Frequency Response Bode Plot				
10	26-11	Design Controller and system compensation	Reports (instrumentatio n in Labview)	DC- motor Kit	Ref-01	5
11	3-12	PID / Design	Quiz	Operational amplifier circuits		5/3 quizes
12	10-12	Optimal and LQR control Fuzzy Logic Control			D 600	
13	17-12	Neural Network (Case study)			Ref-02	
14	24-12	Corrective exam and Receive project				10 for exam 20 for project

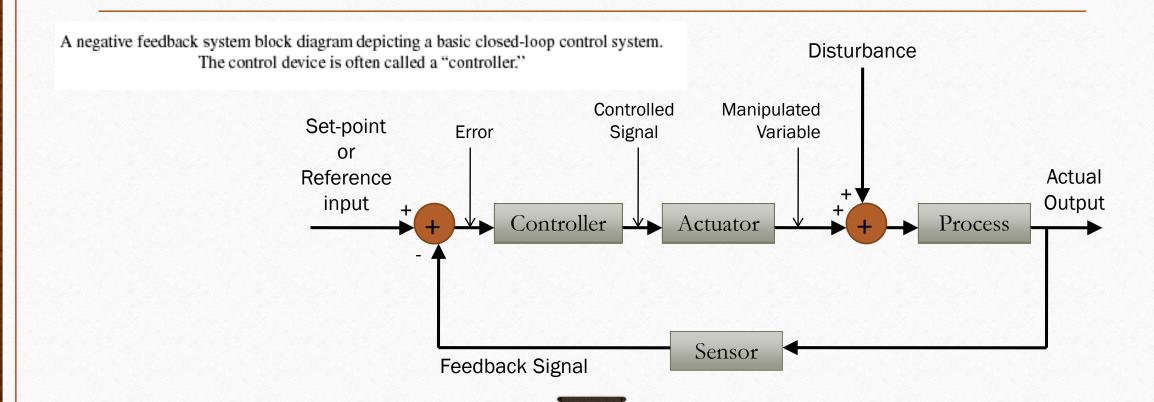
Evaluation rules

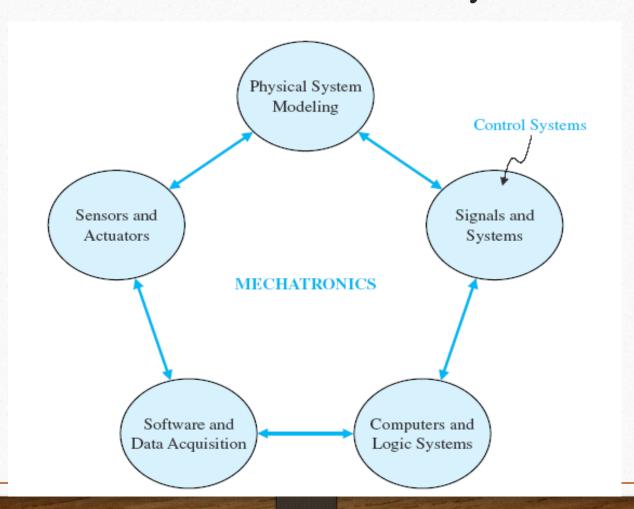
Report Contents

- Research plane
- Problem statement / Aim
- Tools/facilities
- Methodology/control strategy
- Experimental works
- Result/ conclusions

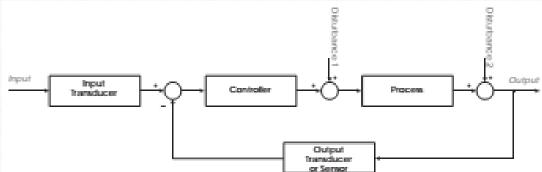
Marks distribution

Marks \	Assessments			Final	Total
assesments				Exam	
	•	MidTerm	15	80	
	•	Projects	20		
	•	Report	5		
	•	quizes	5		
TOTAL			45	80	125





Closed-Loop Control System

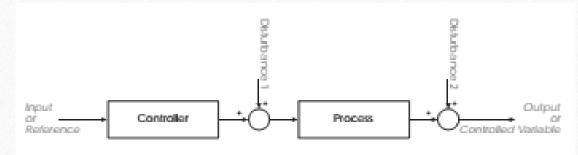


Input temperature dial position converted into a voltage by a potentiometer.

Output temperature converted to a voltage by a thermistor.

Differencing circuit subtracts output from input result is actuating signal controller drives the plant only if there is a difference

Open-Loop Control System



Process is a boiler, input is fuel, output is heat.

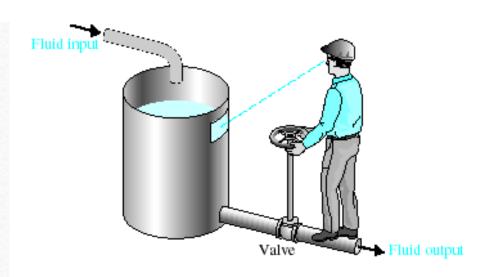
Controller is electronics, valves, etc. that control fuel flow into furnace.

Input is thermostat position



Examples of Modern Control Systems

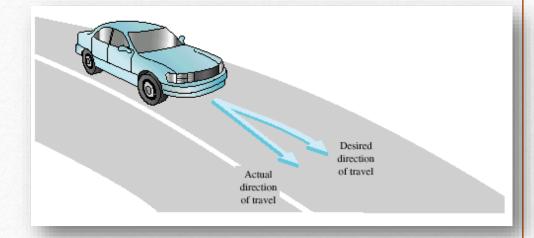
A manual control system for regulating the level of fluid in a tank by adjusting the output valve. The operator views the level of fluid through a port in the side of the tank.



Transportation

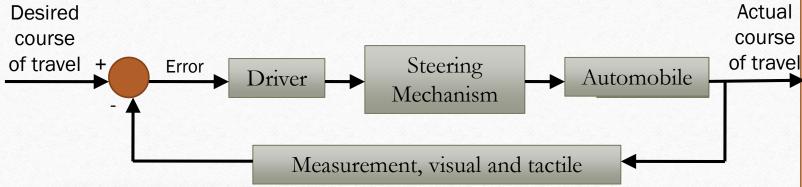
Car and Driver

- Objective: To control direction and speed of car
- Outputs: Actual direction and speed of car
- Control inputs: Road markings and speed signs
- Disturbances: Road surface and grade, wind, obstacles
- Possible subsystems: The car alone, power steering system, breaking system

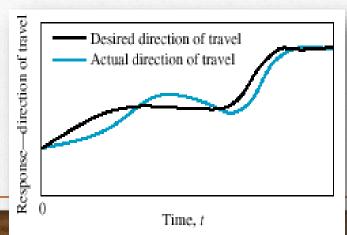


Transportation

• Functional block diagram: Desired



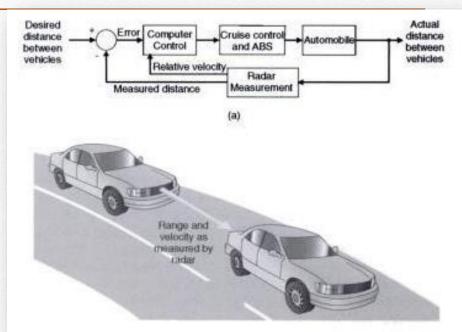
• Time response:



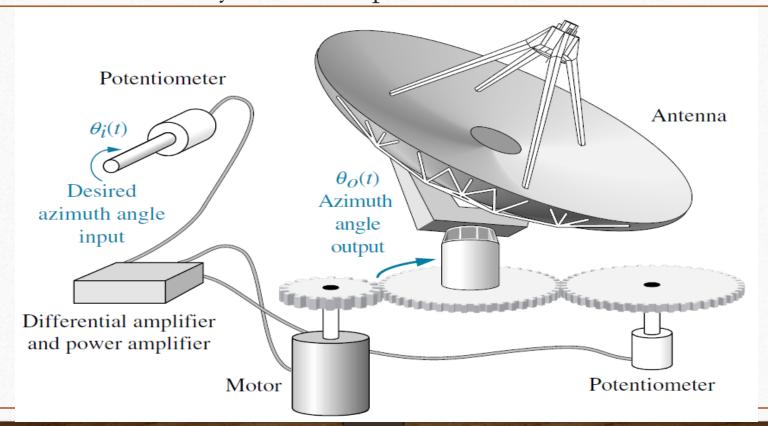
Transportation

• Consider using a radar to measure distance and velocity to autonomously maintain distance between vehicles.

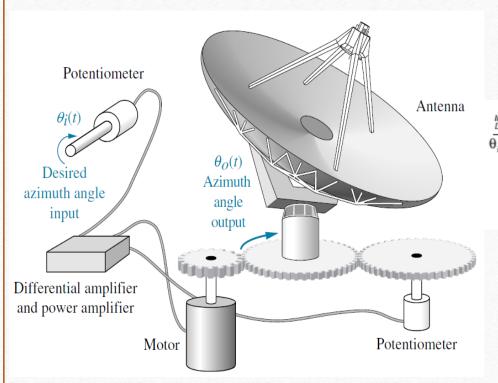
- Automotive: Engine regulation, active suspension, anti-lock breaking system (ABS)
- Steering of missiles, planes, aircraft and ships at sear.

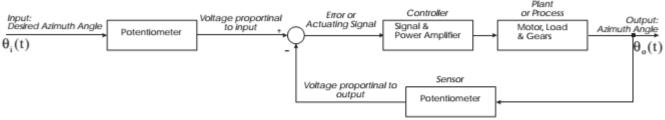


• Azimuth Position Control System Example



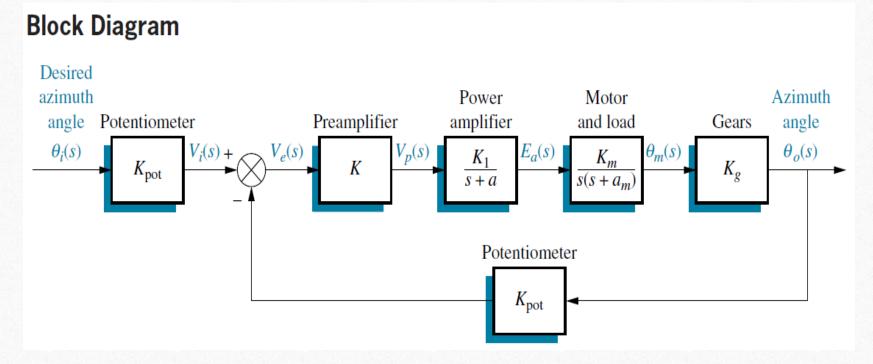
Azimuth Position Control System Example





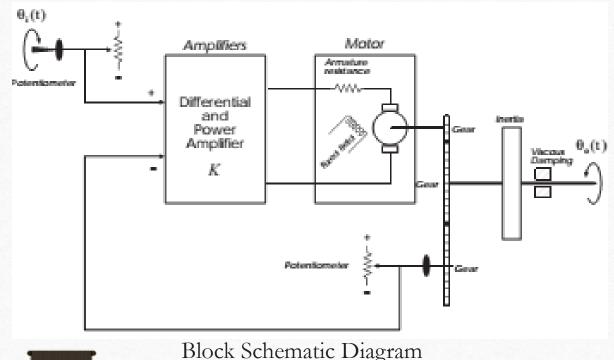
Block Schematic Diagram

Azimuth Position Control System Example



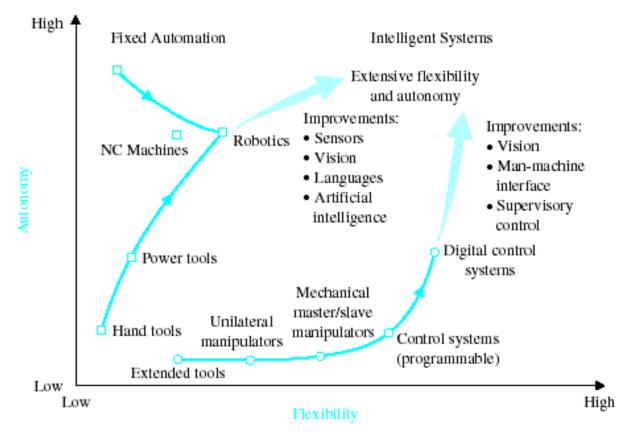
Transform the Physical System into a Schematic

- Makes relationships more concrete
- Enables decisions to be made about what can be neglected in formulating the mathematical model.
- Assumptions made can be easily reviewed and schematic and/or model adjusted as necessary.
- Should be kept as simple as possible:
 - Checked by analysis and simulation
 - Phenomena added if results do not agree with observed behavior



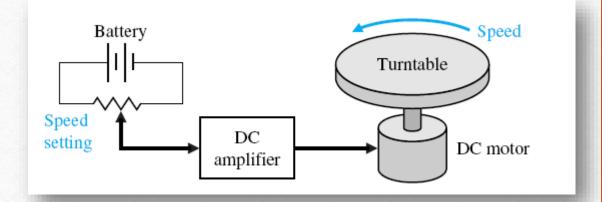
The Future of Control Systems

Future evolution of control systems and robotics.

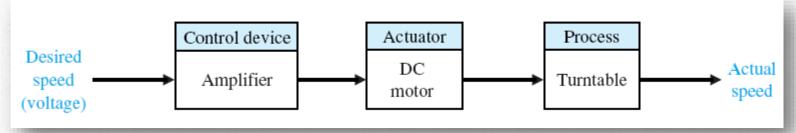


Turntable Speed Control

- Application: CD player, computer disk drive
- Requirement: Constant speed of rotation
- Open loop control system:



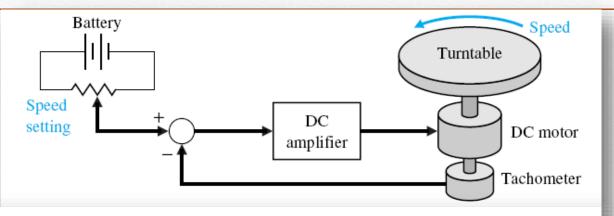
Block diagram representation:

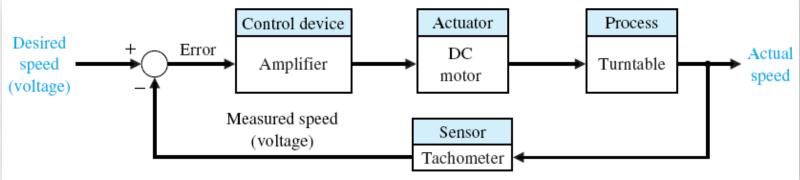


Turntable Speed Control

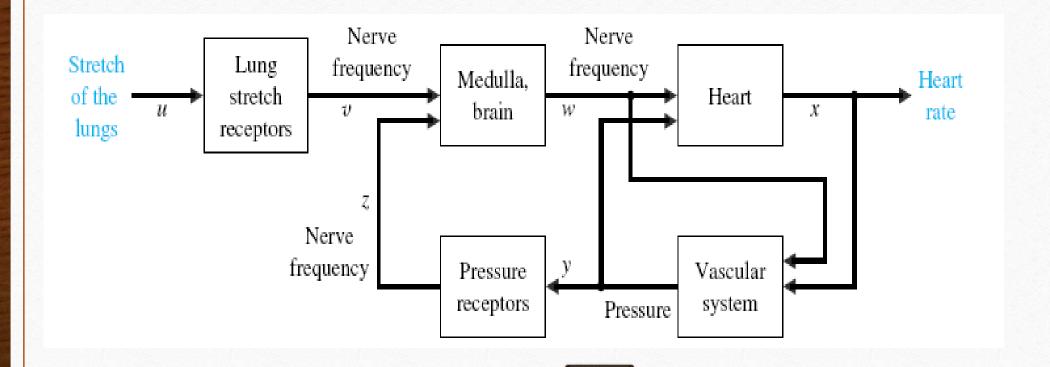
• Closed-loop control system:

• Block diagram representation:

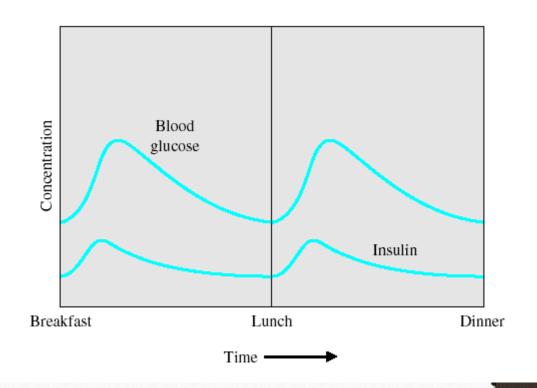




Design Example

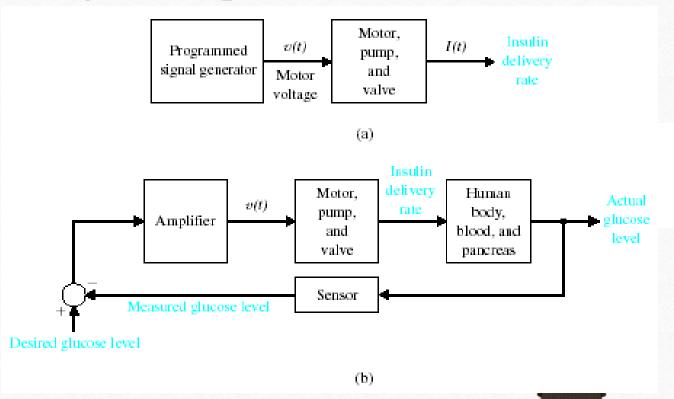


Design Example



The blood glucose and insulin levels for a healthy person.

Design Example



(a) Open-loop (without feedback) control and(b) closed-loop control of blood glucose.

Projects

*Project. 1

process control application in Food drying

https://www.youtube.com/watch? v=TYk97vWyHqc&t=8s

*Project. 2 process control application in waste garbage

		Week 2	Week 3	Week 5	Week 8	Week 10	Week 12
Group 1.1	waste garbage	survey	analysis	design	Manufacturing	Assembly and control	Test
Group 1.2	Food drying	survey	analysis	design	Manufacturing	Assembly and control	Test

Projects

Tutorial

Course material

- •http://52.174.38.133/login/index.php
- http://www.bu.edu.eg/staff/mustafaabdelmonem3-courses/13958

contacts

Mustafa.elsayed@feng.bu.edu.eg